

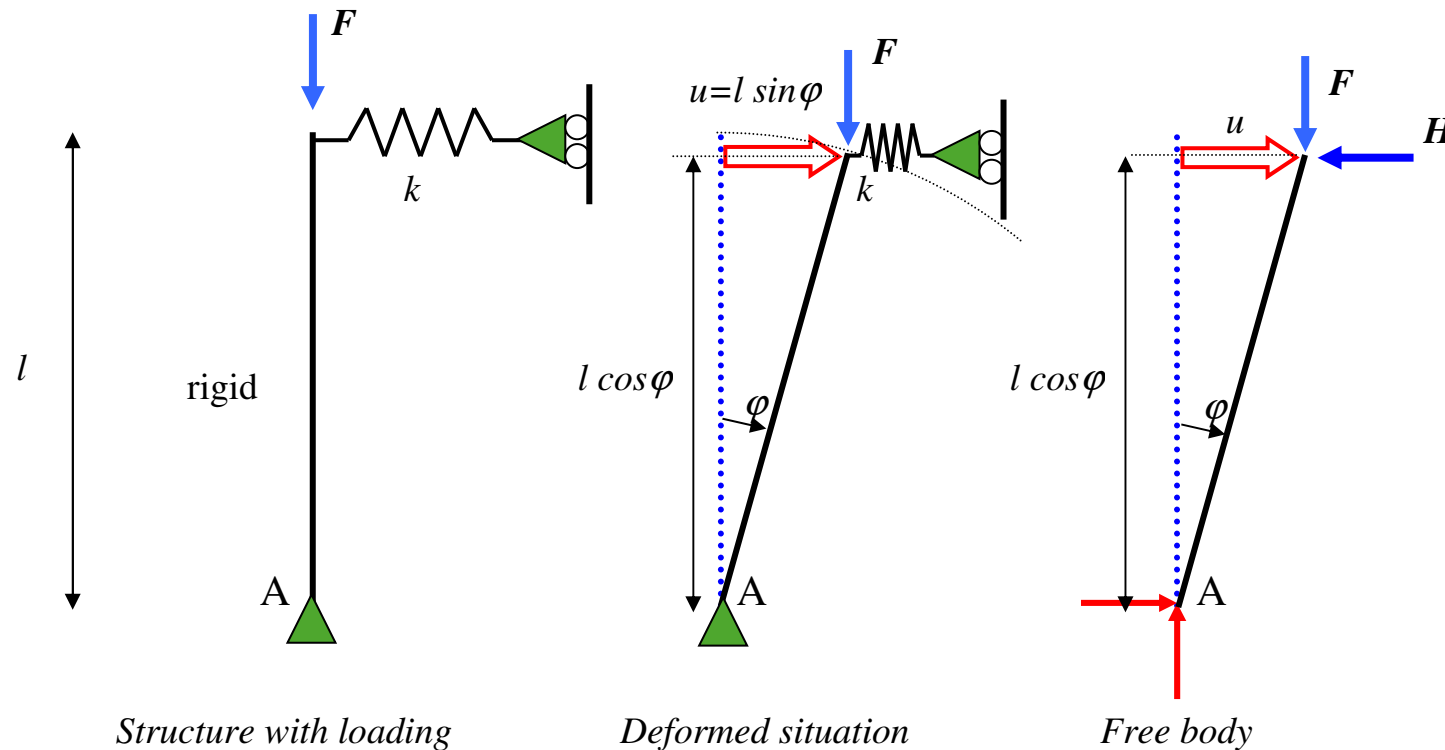
OBJECTIVES OF THIS PART

- 6 2nd order effect and the magnification factor
 - Post-buckling
 - Initial displacement and second order effects – rigid models
 - Initial displacement and second order effects – flexural models

- Stability of equilibrium for large displacements for rigid models
- Examine increase of initial displacement due to action of compressive force in displaced situation for rigid rods
- Model this effect with magnification factor
- Apply this on a structural model
- Check the model for flexural buckling

POST BUCKLING BEHAVIOUR, rigid model 1

(large displacements)



EQUILIBRIUM (large displacements)

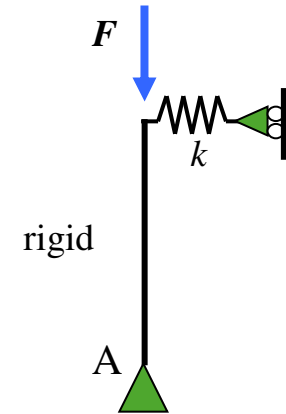
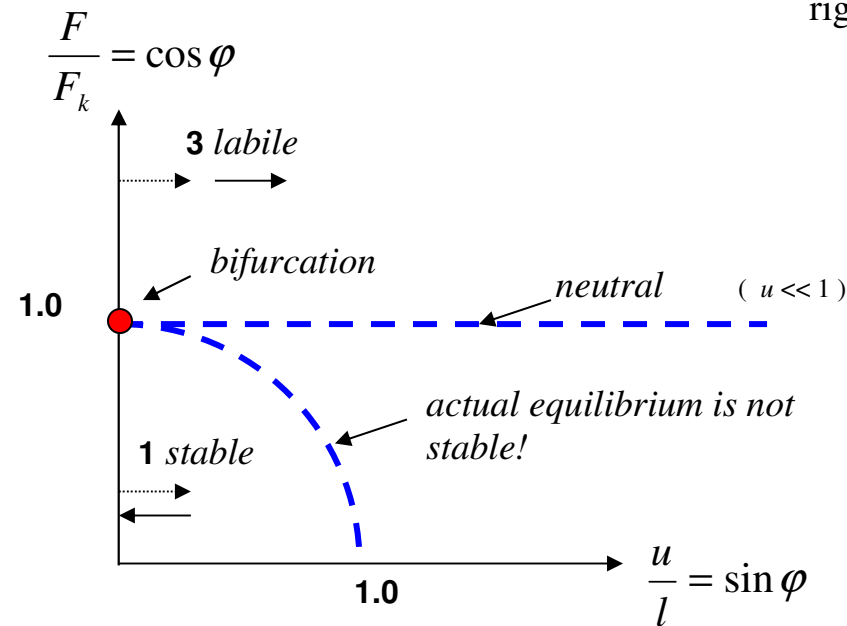
$$F u = H l \cos \varphi$$

$$F u = k u l \cos \varphi$$

$$F = k l \cos \varphi$$

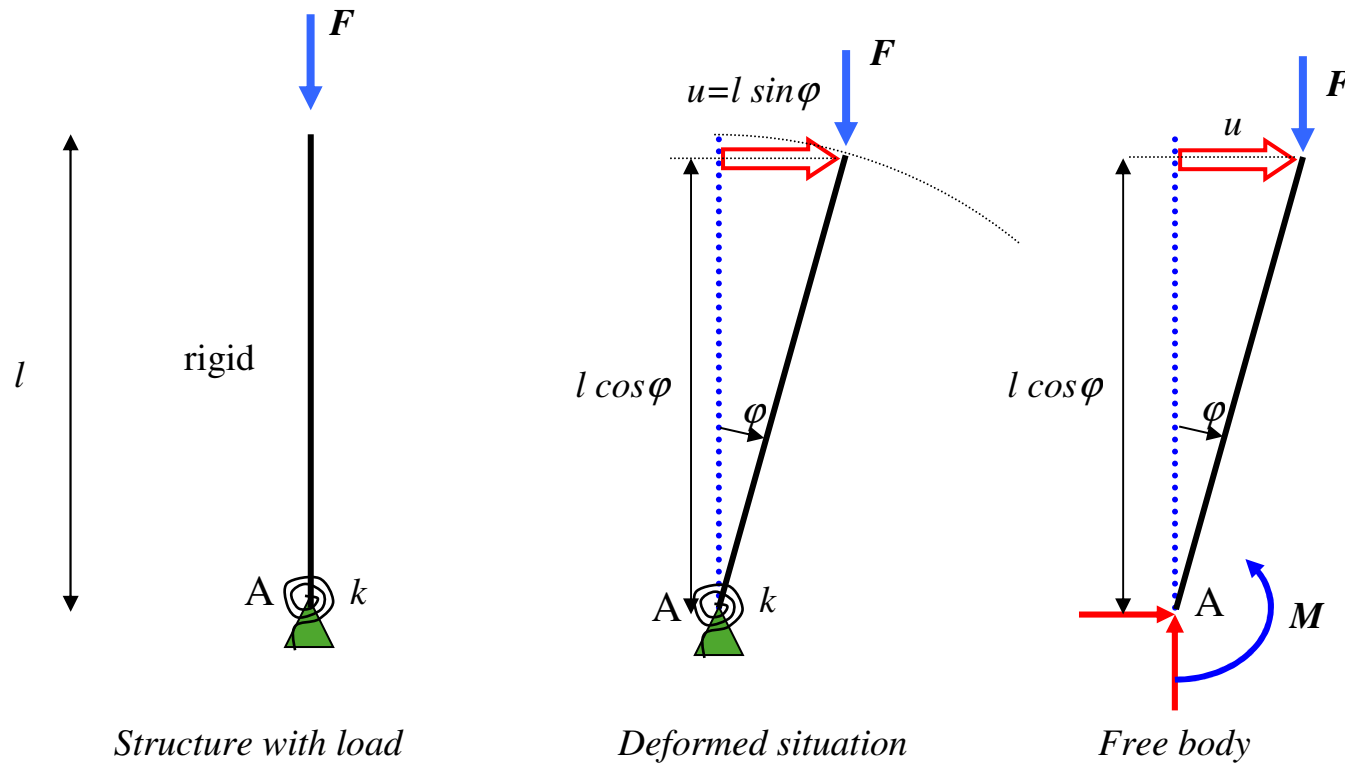
with: $F_k = k l$

$$\frac{F}{F_k} = \cos \varphi$$



POST BUCKLING BEHAVIOUR, rigid model 2

(large displacements)



EQUILIBRIUM (large displacements)

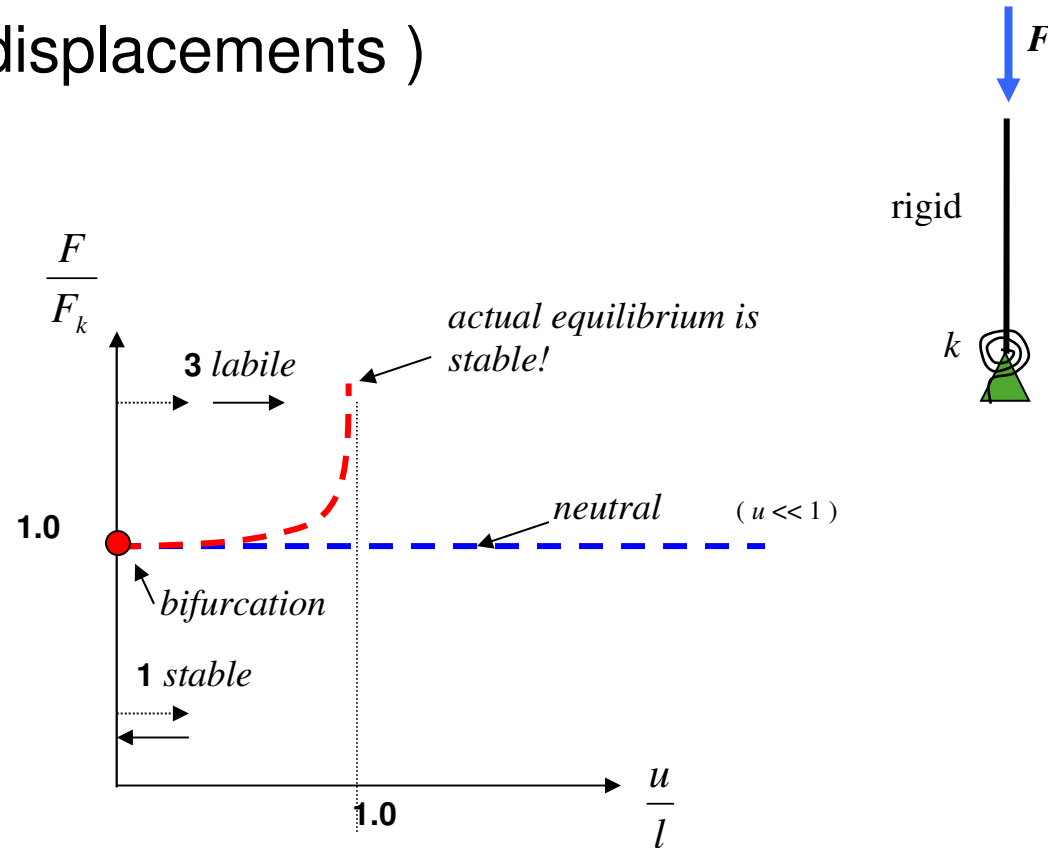
$$F u = M$$

$$F l \sin \varphi = k \varphi$$

$$F = \frac{k}{l} \frac{\varphi}{\sin \varphi}$$

with: $F_k = \frac{k}{l}$

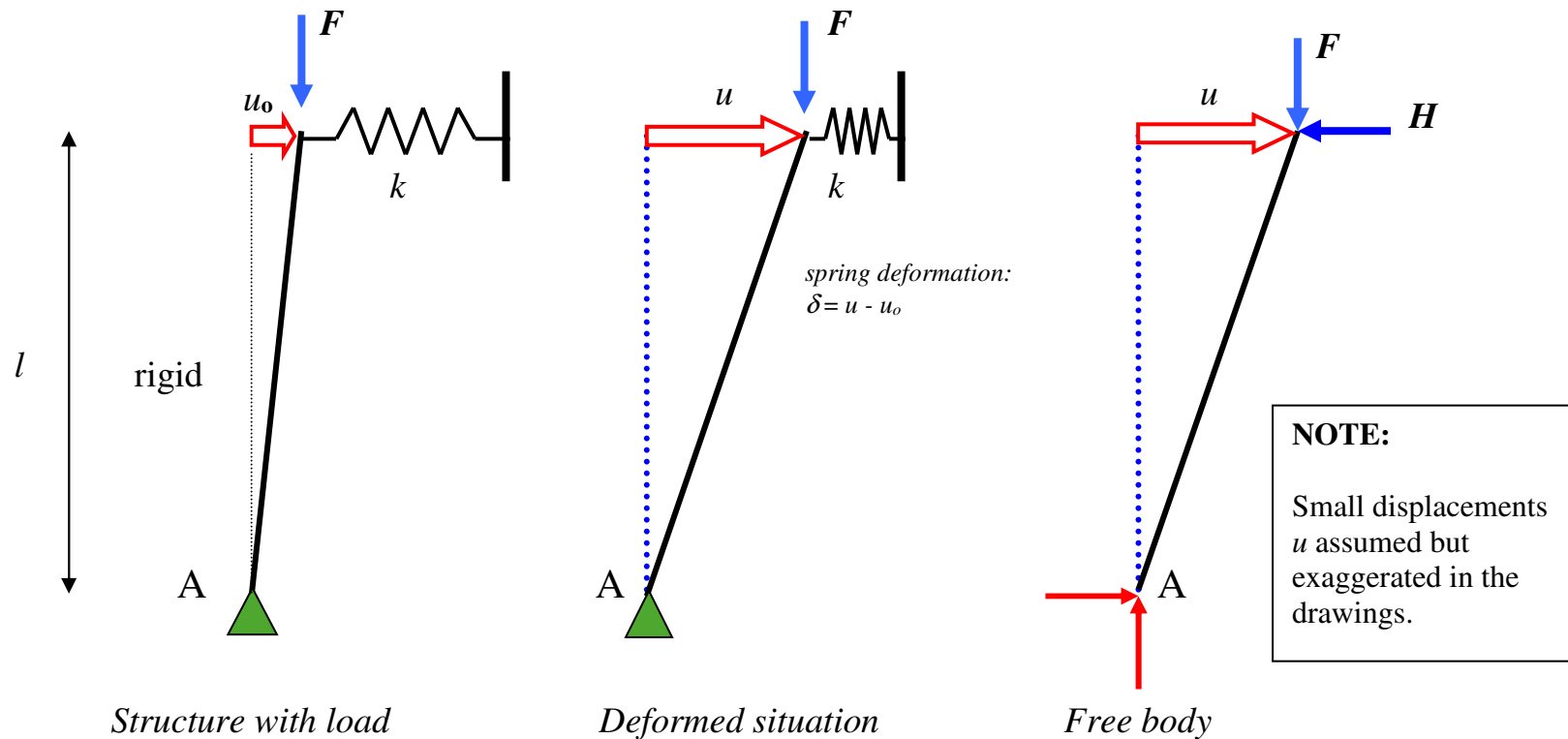
$$\frac{F}{F_k} = \frac{\varphi}{\sin \varphi}$$



INITIAL DISPLACEMENT (magnification factor)

(Chapter 10)

(small displacements, rigid model)



ELABORATE

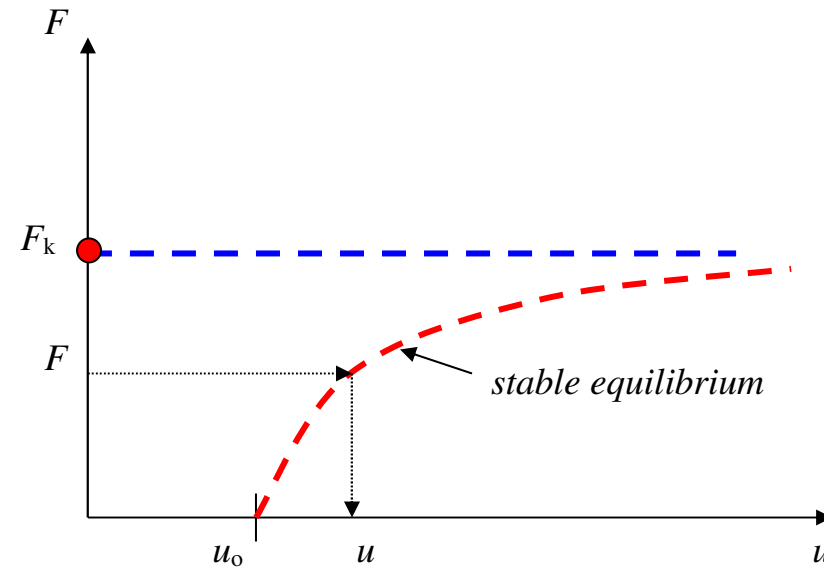
$$F u = H l = k l (u - u_o) \quad \Leftrightarrow$$

$$\frac{F}{F_k} = \frac{u - u_o}{u} = 1 - \frac{u_o}{u} \quad \Leftrightarrow$$

$$u = \left(\frac{F_k}{F_k - F} \right) u_o \quad \text{define : } n = \frac{F_k}{F}$$

$$u = \left(\frac{n}{n-1} \right) u_o$$

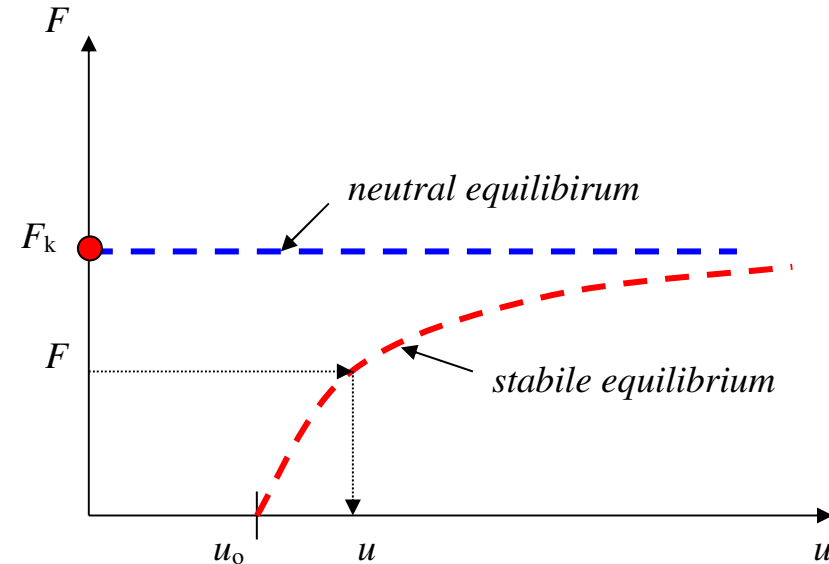
magnification factor



IMPORTANT CONCEPTS

(found for rigid models)

- Buckling load
- Initial displacement
 - 1st order displacement, linear calculation
 - 2nd order displacement, Geometrical non-linear calculation (GNL)
- Magnification factor

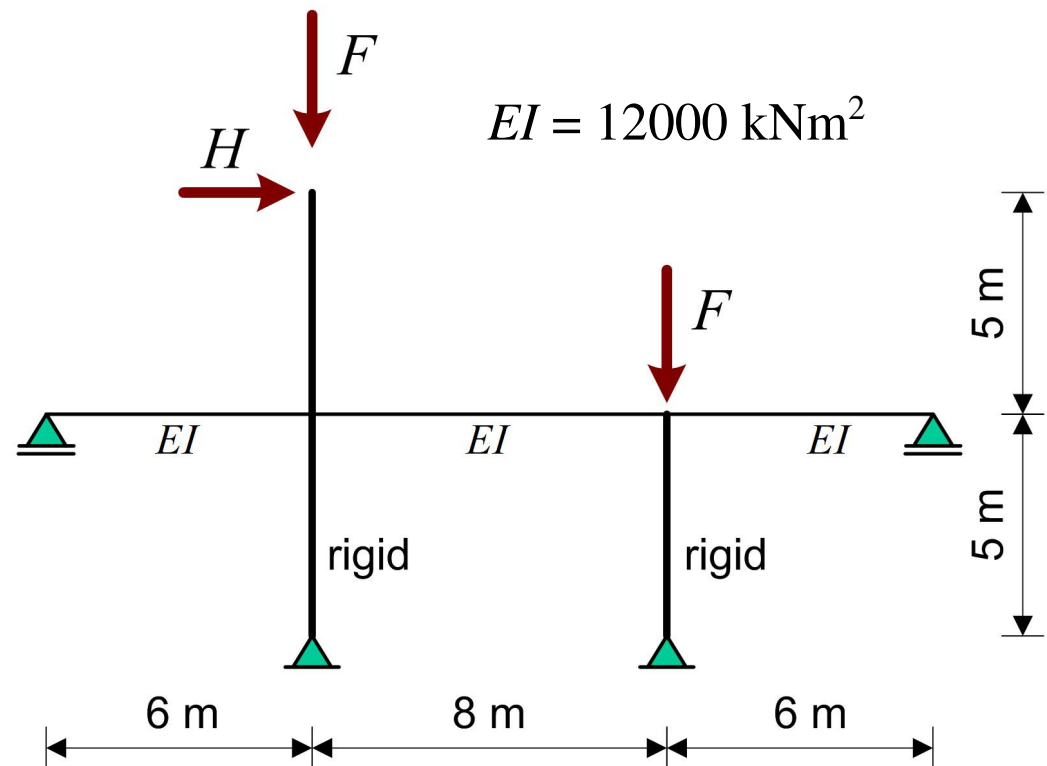


EXAMPLE: INITIAL DISPLACEMENT
due to a horizontal load

assume :
 $u \ll 1$

Question:

- Critical load F_c
- Find u for $H = 12$ kN; $F = 0$ kN (1st order calculation)
- Find u for $H = 12$ kN ; $F = 1000$ kN (2nd order calculation)
- Draw *load - displacement* diagram (for $H = 12$ kN)



MAGNIFICATION FACTOR, flexural models

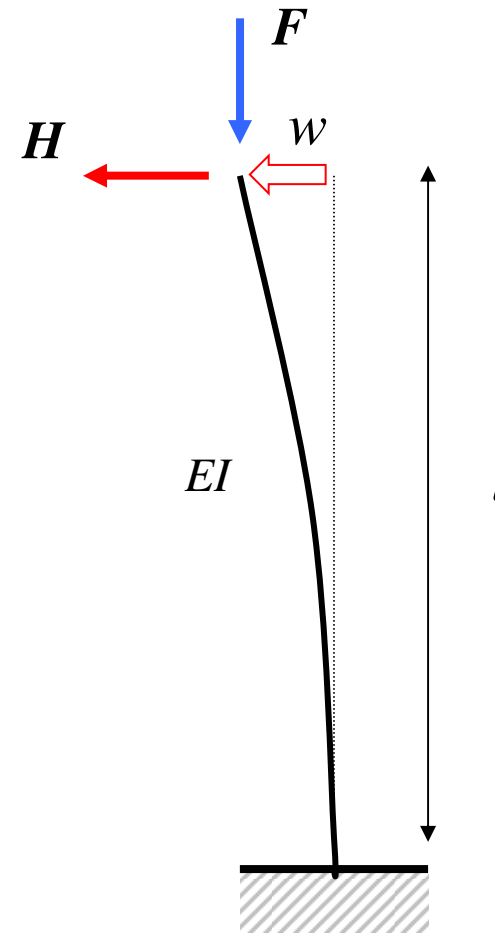
(Chapter 11)

EXAMPLE

Find the influence of the vertical load F on the horizontal deflection w , initiated by H .

1st order deflection:

$$w_o = \frac{Hl^3}{3EI} \Rightarrow H = \frac{3EI}{l^3} w_o$$



TOOLING 2nd order calculation

$$EIw'''' + Fw'' = 0 \quad (q_x, q_z = 0)$$

and

$$S_z = M' - Fw'$$

General solution:

$$w(x) = C_1 + C_2x + C_3 \cos \alpha x + C_4 \sin \alpha x$$

- 4th order ODE
- 4 boundary conditions

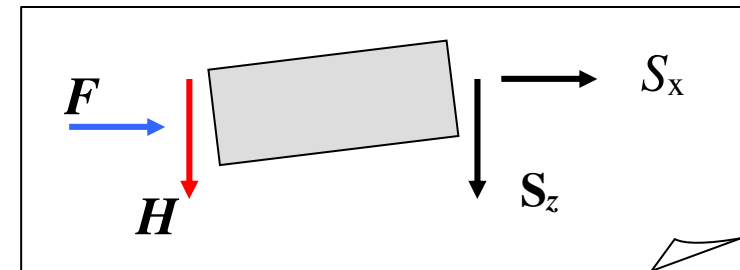
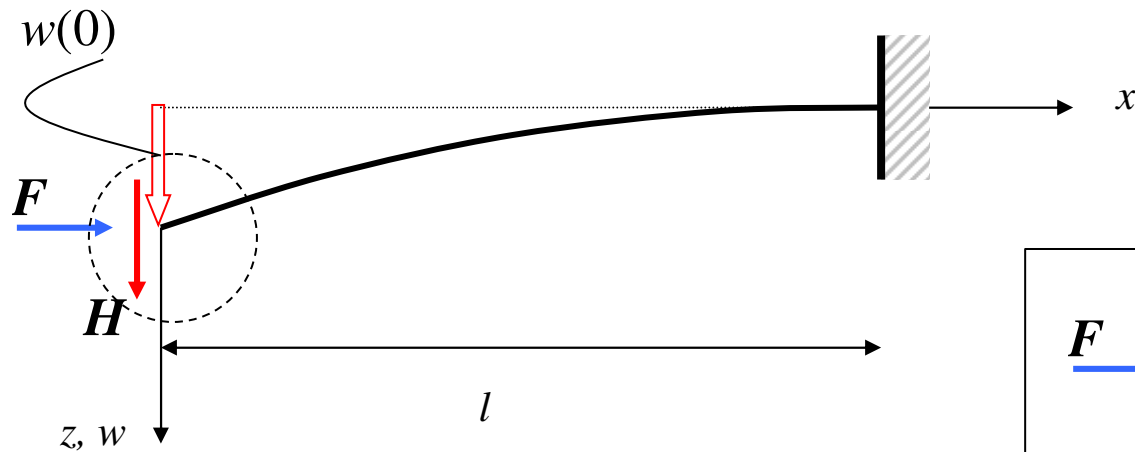
Some derivatives to elaborate boundary conditions:

$$w(x) = C_1 + C_2x + C_3 \cos \alpha x + C_4 \sin \alpha x$$

$$w'(x) = C_2 - \alpha C_3 \sin \alpha x + \alpha C_4 \cos \alpha x \quad S_z = -EIw'''' - Fw' = -FC_2$$

$$w''(x) = -\alpha^2 C_3 \cos \alpha x - \alpha^2 C_4 \sin \alpha x$$

EQUILIBRIUM



$$w'''' + \alpha^2 w'' = 0 \quad \text{with:} \quad \alpha^2 = \frac{F}{EI}$$

$$S_z = M' - Fw' \Leftrightarrow S_z = -EIw''' - Fw'$$

Boundary conditions:

- | | |
|------------------|---------------------|
| 1) $S_z(0) = -H$ | 3) $w(l) = 0$ |
| 2) $M(0) = 0$ | 4) $\varphi(l) = 0$ |

System of equations from BC:

- 1) $-FC_2 = -H \Rightarrow C_2 = H / F$
- 2) $EI\alpha^2 C_3 = 0 \Rightarrow C_3 = 0$
- 3) $C_1 + C_2 l + C_3 \cos \alpha l + C_4 \sin \alpha l = 0$
- 4) $C_2 - \alpha C_3 \sin \alpha l + \alpha C_4 \cos \alpha l = 0$

Result:

- 1) $C_2 = H / F$
- 2) $C_3 = 0$
- 3) $C_1 = \frac{H}{F} \left(\frac{\tan \alpha l}{\alpha} - l \right)$
- 4) $C_4 = -\frac{H}{F \alpha \cos \alpha l}$

SOLUTION:

$$w(x) = \frac{H}{F} \left(\frac{\tan \alpha l}{\alpha} - l \right) + \frac{H}{F} x - \frac{H}{F} \frac{\sin \alpha x}{\alpha \cos \alpha l} \quad \text{with: } \alpha^2 = \frac{F}{EI}$$

EXACT DEFLECTION IS FOUND FOR GIVEN F and H !

Not a buckling problem but a 2nd order calculation!

2nd ORDER DEFLECTION AT FREE END ($x = 0$) :

$$w(0) = \frac{H}{F} \left(\frac{\tan \alpha l}{\alpha} - l \right) \quad \text{with:} \quad H = \frac{3EI}{l^3} w_o$$

$$w(0) = \frac{Hl}{F} \left(\frac{\tan \alpha l}{\alpha l} - 1 \right) = \frac{3EI}{l^2 F} \left(\frac{\tan \alpha l}{\alpha l} - 1 \right) w_o$$

$$w(0) = \frac{3}{(\alpha l)^2} \left(\frac{\tan \alpha l}{\alpha l} - 1 \right) w_o$$

 exact magnification factor

MAGNIFICATION FACTOR

$$\text{rigid models} = \frac{n}{n-1}$$

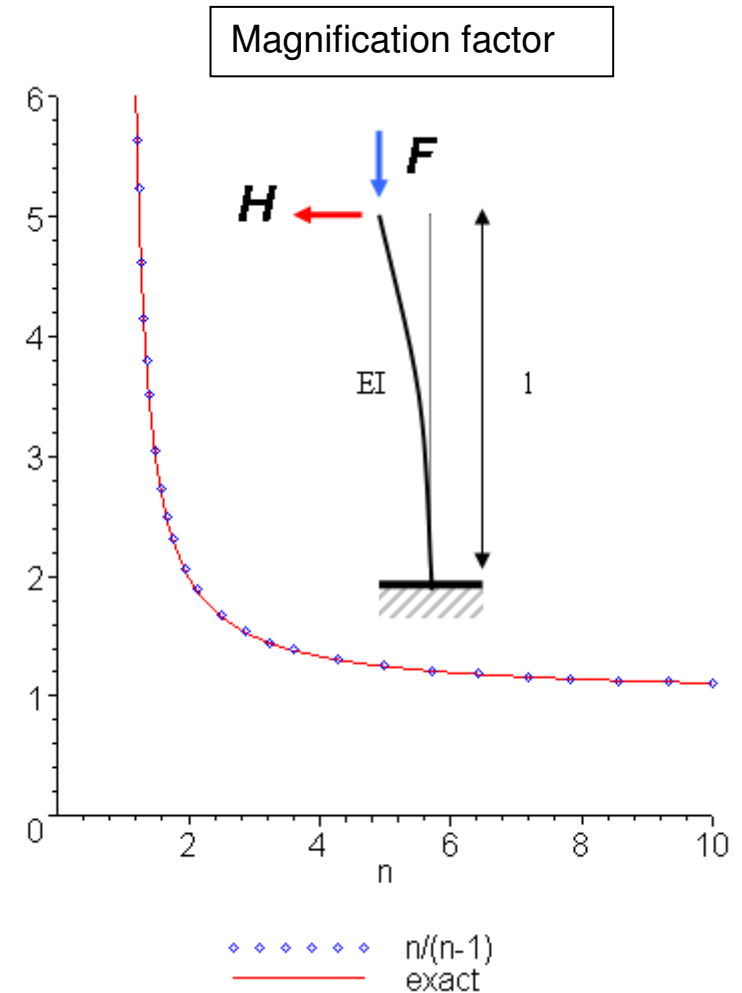
$$\text{exact} = \frac{3}{(\alpha l)^2} \left[\frac{\tan(\alpha l)}{\alpha l} - 1 \right]$$

with:

$$n = \frac{F_k}{F} = \frac{\pi^2 EI}{4l^2 \alpha^2 EI} = \frac{\pi^2}{4(\alpha l)^2}$$

$$(\alpha l) = \frac{\pi}{2\sqrt{n}}$$

Conclusion: $\frac{n}{n-1}$ fits very well?



RESULTS EXAMPLE

n	αl	$exact$	$n/(n-1)$
1,01	1,56	99,56	101,00
1,05	1,53	20,71	21,00
1,25	1,40	4,94	5,00
1,50	1,28	2,97	3,00
1,75	1,19	2,31	2,33
2,00	1,11	1,99	2,00
2,50	0,99	1,66	1,67
5,00	0,70	1,25	1,25
7,50	0,57	1,15	1,15
10,00	0,50	1,11	1,11

Good match but with small differences.

Is there an explanation?

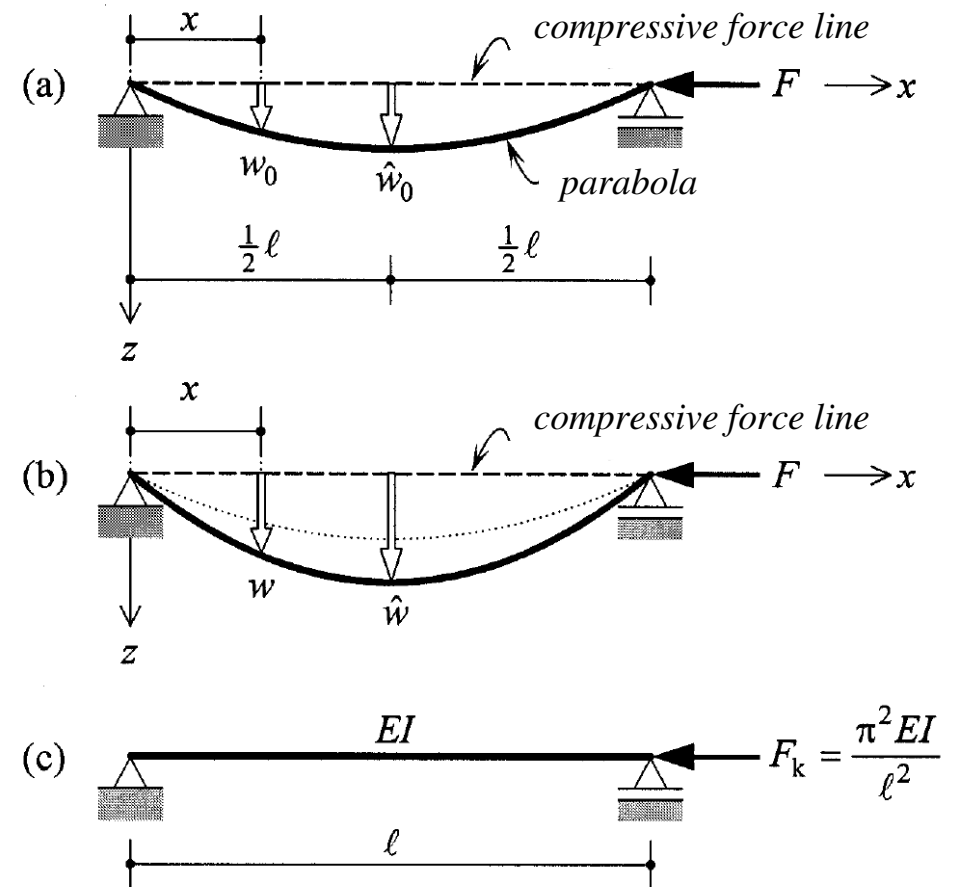
EXAMPLE (par 11.2.2)

- parabolic initial deflection

Very good approximation:

$$\frac{n}{n-1}$$

Conclusion: $\frac{n}{n-1}$ fits very well?



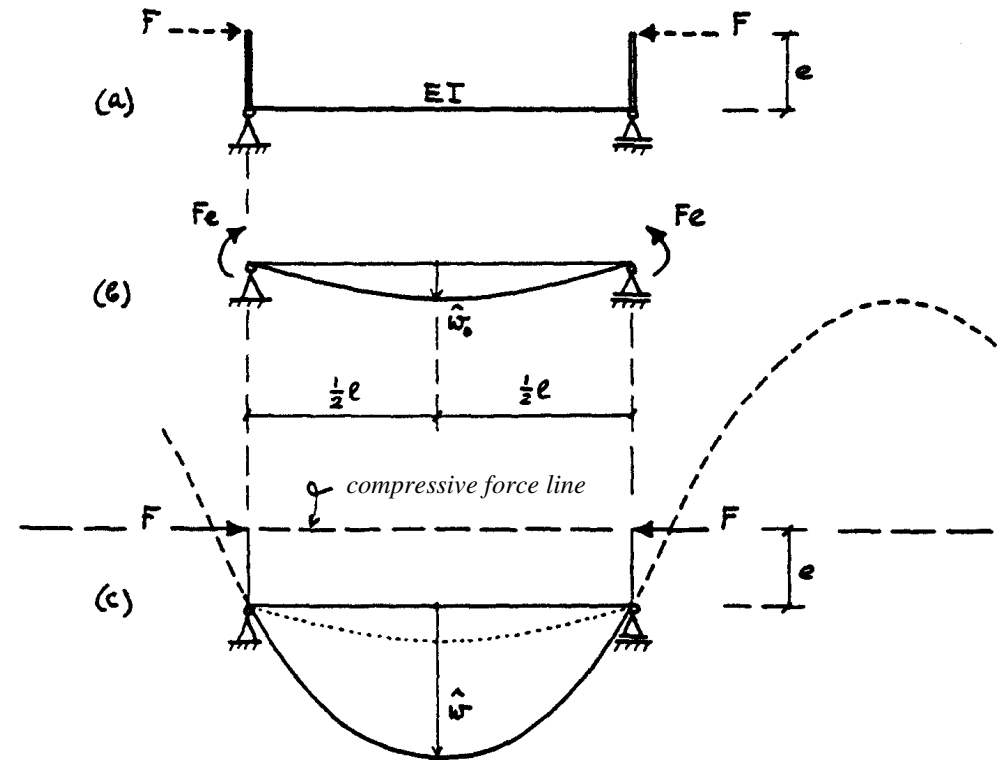
EXAMPLE

Excentric compressive force

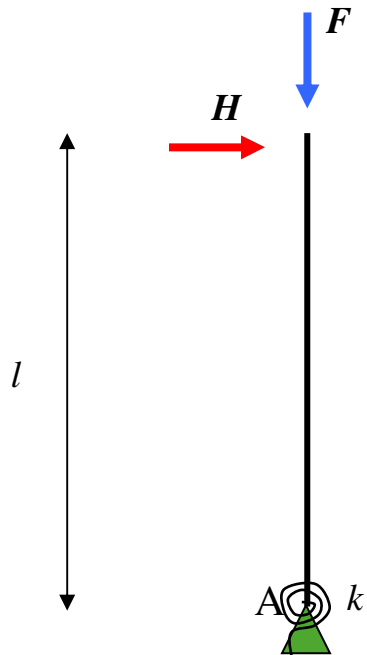
Approximation:

Magnification factor for *bending moment* at midspan:

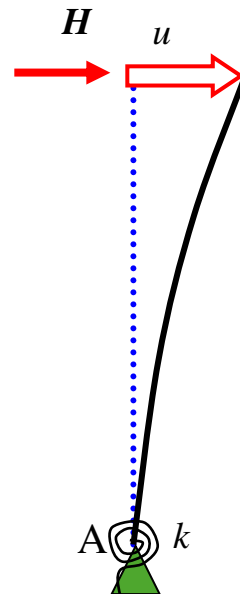
$$\frac{n + 0,25}{n - 1}$$



EXAMPLE 2nd order BENDING MOMENT (par 11.3.3)



Structure with loads



Linear result, 1st order

1st order deflection:
(due to H:)

$$u_o = \frac{Hl^3}{3EI} + \frac{(Hl)l}{r} \text{ define: } \rho = \frac{kl}{EI}$$

$$u_o = Hl \times \frac{l^2}{3EI} \left(1 + \frac{3}{\rho} \right)$$

$$u_o = \frac{l^2}{3EI} \left(1 + \frac{3}{\rho} \right) M_o \quad \text{with: } M_o = Hl$$

2nd ORDER MOMENT

Moment in the spring due to the total load in the deformed situation (GNL).

2nd order moment in the rotational spring:

$$M = Hl + F u = Hl + F \frac{n}{n-1} u_o = Hl + \frac{nF}{n-1} Hl \frac{l^2}{3EI} \left(1 + \frac{3}{\rho} \right)$$

$$M = M_o \left(1 + \frac{nF}{n-1} \frac{l^2}{3EI} \left(1 + \frac{3}{\rho} \right) \right) = M_o \left(\frac{n-1 + nF \frac{l^2}{3EI} \left(1 + \frac{3}{\rho} \right)}{n-1} \right) \quad \text{with: } n = \frac{F_k}{F}$$

$$M = M_o \left(\frac{n-1 + \frac{F_k l^2}{3EI} \left(1 + \frac{3}{\rho} \right)}{n-1} \right) \quad \text{with: } F_k = \frac{\pi^2 EI}{l^2 \left(4 + \frac{\pi^2}{\rho} \right)}$$

ELABORATE THIS RESULT

2nd order moment in the spring:

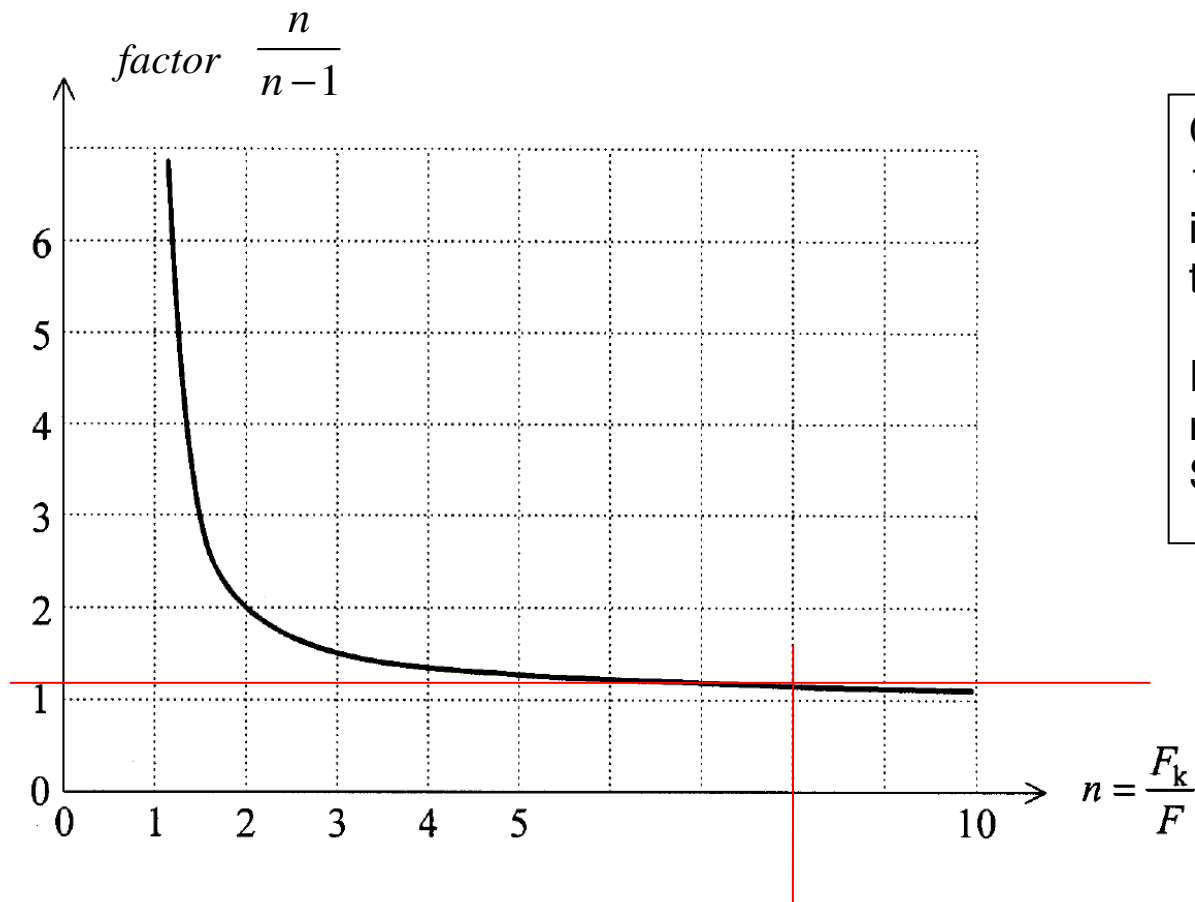
$$M = M_o \left(\frac{n-1 + \frac{\pi^2 E I l^2 \left(1 + \frac{3}{\rho}\right)}{3 E I l^2 \left(4 + \frac{\pi^2}{\rho}\right)}}{n-1} \right) = M_o \left(\frac{n-1 + \frac{\pi^2 \left(1 + \frac{3}{\rho}\right)}{3 \left(4 + \frac{\pi^2}{\rho}\right)}}{n-1} \right) \quad \text{with: } \pi^2 \approx 10$$

Not expected ...

$$M = \frac{n - \frac{0,2\rho}{1.2\rho + 3}}{n-1} M_o \quad \text{magnification factor for the moment :}$$

$$\frac{n - \frac{\rho}{3(5 + 2\rho)}}{n-1}$$

ACCEPTABLE MAGNIFICATION FACTOR



Choose as a limit max 15% magnification of the initial displacement due to the compressive force.

Engineering code has rules for this, see lectures Steel and Concrete.

$$\frac{n}{n-1} \leq 1,15 \quad \Leftrightarrow \quad n \geq 8 \quad \Rightarrow \quad F_{\max} \leq 0,125 F_k \quad (\text{max } 12,5\% \text{ of } F_k !!)$$

CONCLUSIONS

MAGNIFICATION FACTOR USING FLEXURAL MODELS

- Standard approach for rigid models is sufficient accurate,
- Although the factor $\frac{n}{n-1}$ is not exact since 2nd order deflection is not affine with 1st order deflection,
- Pay attention for some special cases in which end-moments depend on the compressive force,
- Limits to the influence of the magnification reduced allowed compressive force considerable.
(never a design load near the buckling load)
(a very exact calculation of the buckling load becomes then also less relevant)

EXAMPLES

