

Lecture 3 :

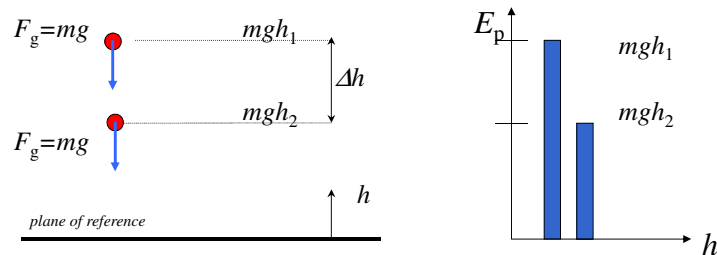
Potential Energy

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http://icocet.tudelft.nl/TUD_CT/

v2021-3

Potential Energy



no kinetic energy (statics)

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Work and Energy methods

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Total Energy

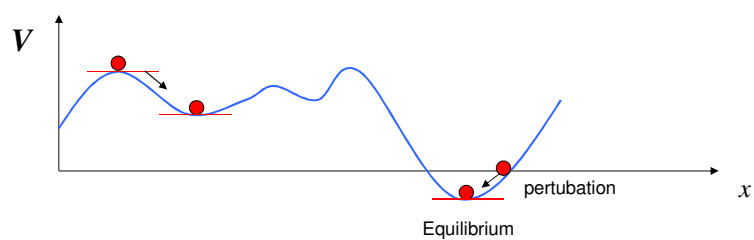
- Sum of all energy in a system is constant
- Sum of all Potential energy = C
- Potential energy:
 - Loads (energy with respect to reference, reduces)
 - Strain energie (E_v , increases)

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Stable Equilibrium



Stationary Energy Function (hor. tangent)

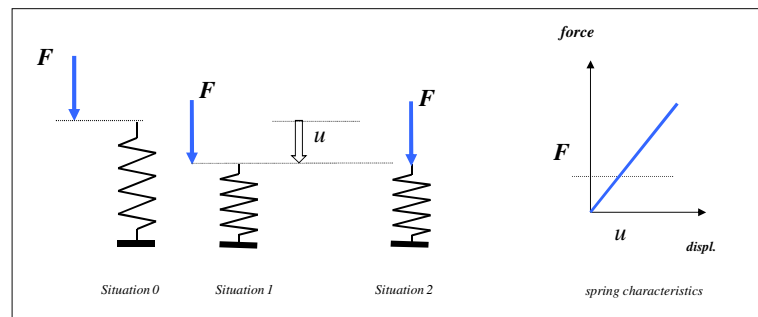
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Potential Energy due to Loads

Load Potential



$$V = E_v - \Delta E_p = \frac{1}{2} \times k \times u^2 - F \times u$$

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Stationary Energy Function at a Minimum Energy level

- Extreme = derivative with respect to a state variable (u) must be zero
- Extreme is a minimum = 2nd deriv > 0

$$\frac{dV}{du} = k \times u - F = 0 \quad \text{and} \quad \frac{d^2V}{du^2} = k \quad (> 0 \text{ is minimum})$$

principle of minimum potential energy

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Application

- Approximate displacement field
- Demand Stationary Potential Energy:
derivative(s) of V with respect to all state variables a_i must be zero.

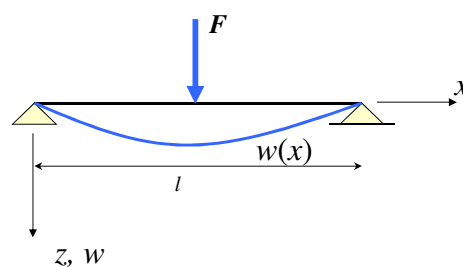
$$\delta V = \frac{\partial V}{\partial a_1} \delta a_1 + \frac{\partial V}{\partial a_2} \delta a_2 + \dots + \frac{\partial V}{\partial a_i} \delta a_i = 0$$

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Example : Beam



$$w = a \sin\left(\frac{\pi x}{l}\right)$$

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Solution

$$\sin^2 a = \frac{1}{2} - \frac{1}{2} \cos 2a$$

$$V = \frac{1}{2} EI \int_0^l w''^2 dx - Fa = \frac{1}{2} \frac{\pi^4 EI a^2}{l^4} \int_0^l \sin^2 \left(\frac{\pi x}{l} \right) dx - Fa$$

$$V = \frac{1}{2} \frac{\pi^4 EI a^2}{l^4} \int_0^l \left(\frac{1}{2} - \frac{1}{2} \cos \left(\frac{2\pi x}{l} \right) \right) dx - Fa = \frac{1}{2} \frac{\pi^4 EI a^2}{l^4} \times \frac{1}{2} l - Fa$$

$$V = \frac{\pi^4 EI a^2}{4l^3} - Fa$$

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Minimalise

$$\frac{dV}{da} = \frac{\pi^4 EI a}{2l^3} - F = 0 \Rightarrow$$

$$w_{mid-span} = a = \frac{Fl^3}{(\pi^4 / 2) EI} = \frac{Fl^3}{48.705 EI}$$

$$V = -\frac{F^2 l^3}{97.409 EI}$$

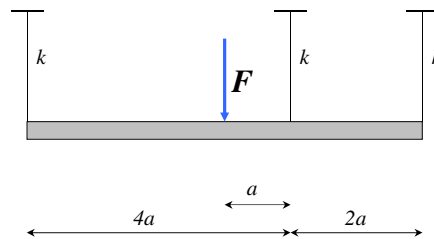
approximation

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Example : Rigid Block

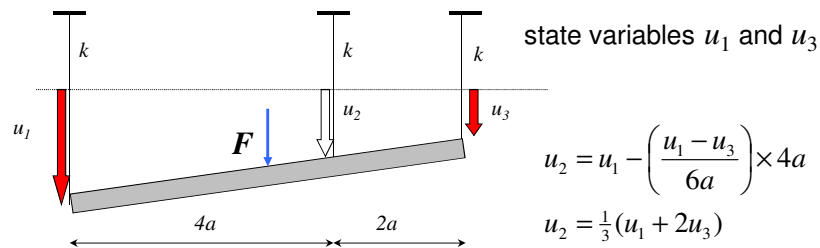


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Displacement field u (assumption)



$$V = \frac{1}{2}ku_1^2 + \frac{1}{2}k\left(\frac{1}{3}(u_1 + 2u_3)\right)^2 + \frac{1}{2}ku_3^2 - F \times \left(\frac{1}{2}(u_1 + u_3)\right) \Leftrightarrow$$

$$V = \frac{10}{18}ku_1^2 + \frac{4}{18}ku_1u_3 + \frac{13}{18}ku_3^2 - \frac{1}{2}F(u_1 + u_3)$$

$$\delta V = \frac{\partial V}{\partial u_1} \delta u_1 + \frac{\partial V}{\partial u_3} \delta u_3 = 0 \rightarrow \frac{\partial V}{\partial u_1} = 0; \quad \frac{\partial V}{\partial u_3} = 0$$

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Result

$$\frac{20}{18}ku_1 + \frac{4}{18}ku_3 - \frac{1}{2}F = 0$$

$$\frac{4}{18}ku_1 + \frac{26}{18}ku_3 - \frac{1}{2}F = 0 \quad \Rightarrow u_3 = \frac{8}{11}u_1;$$

$$u_1 = \frac{11}{28} \frac{F}{k} \quad u_2 = \frac{9}{28} \frac{F}{k} \quad u_3 = \frac{8}{28} \frac{F}{k}$$

exact solution

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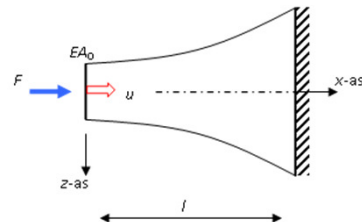
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Assignment

$$EA(x) = \frac{2EA_o}{2 - \frac{x}{l}}$$

Assume a displacement field:

$$u(x) = a \left(1 - \frac{x}{l} \right)$$

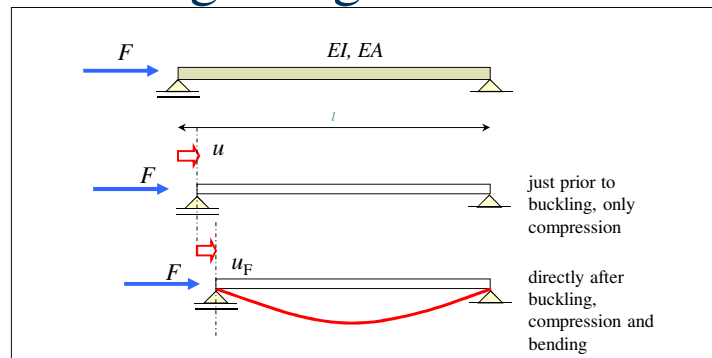


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Application Potential Energy Buckling ... again



assume: $w = a \sin\left(\frac{\pi x}{l}\right)$

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Stationary potential energy:

$$V = \frac{1}{2} EI \int_0^l w''^2 dx - F u_F = \frac{1}{2} EI \int_0^l w''^2 dx - F \frac{1}{2} \int_0^l (w')^2 dx$$

$$V = \frac{\pi^4 EI a^2}{4l^3} - \frac{\pi^2 F a^2}{4l}$$

$$\frac{dV}{da} = \frac{\pi^4 EI a}{2l^3} - \frac{\pi^2 F a}{2l} = 0 \Rightarrow F_k = \frac{\pi^2 EI}{l^2}$$

```
> restart;
> w:=a*sin(Pi*x/L);
> V:=EI*int((1/2)*diff(w,x$2)^2,x=0..L)-F*int((1/2)*diff(w,x)^2,x=0..L);
> eq:=diff(V,a)=0;
> solve(eq,F);
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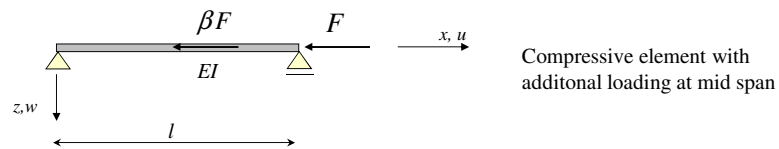
What about a ?

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Assignment, F_k with Pot. Energy?



Approach Potential Energy: (versus Rayleigh method)

- Assume a kinematically admissible displacement field
- Potential energy due to deformation
- Potential energy due to loads
- Apply min Pot. Energy principle

answer :

$$F_k = \frac{2\pi^2 EI}{(\beta + 2)l^2}$$

$$F_k = \alpha \frac{\pi^2 EI}{l^2} \quad \text{with: } \alpha = \frac{2}{\beta + 2}$$